

THE QUADRIC OF WILCZYNSKI

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The purpose of this note is to state and prove a theorem concerning the quadric of Wilczynski. In the first place, let S be a non-ruled surface in ordinary projective space. If the asymptotic curves are chosen as parametric, then S is an integral surface of a pair of differential equations which can be written in the Fubini canonical form [1]¹

$$(1) \quad x_{uu} = px + \theta_u x_u + \beta x_v, \quad x_{vv} = qx + \gamma x_u + \theta_v x_v \quad (\theta = \log \beta \gamma),$$

in which subscripts indicate partial differentiation, and the coefficients are functions of u, v . We select an ordinary point P_x of the surface S as one vertex of the usual local tetrahedron of reference whose vertices are the points x, x_u, x_v, x_{uv} .

Two lines $\bar{L}_1(a, b), \bar{L}_2(a, b)$ are reciprocal lines at a point P_x of the surface if the line $\bar{L}_1(a, b)$ joins the point P_x and the point y defined by

$$(2) \quad y = -ax_u - bx_v + x_{uv}$$

and the line $\bar{L}_2(a, b)$ joins the points ρ, σ defined by placing

$$(3) \quad \rho = x_u - bx, \quad \sigma = x_v - ax,$$

where a, b are functions of u, v . It follows from equations (3) that

$$(4) \quad \begin{aligned} \rho_v &= -(b_v + ab)x - b\sigma + x_{uv}, \\ \sigma_u &= -(a_u + ab)x - a\rho + x_{uv} \end{aligned}$$

The lines $\rho\rho_v$ and $\sigma\sigma_u$ intersect the line $\bar{L}_1(a, b)$ in the respective points

$$(5) \quad (ab - b_v)x + y, \quad (ab - a_u)x + y.$$

The harmonic conjugate of the point P_x with respect to these two points is the point whose local coordinates are

$$(6) \quad \begin{aligned} x_1 &= ab - \frac{1}{2}(a_u + b_v), \\ x_2 &= -a, \\ x_3 &= -b, \\ x_4 &= 1. \end{aligned}$$

¹Lane, E. P. 1942. *A treatise on projective differential geometry*. Chicago.

We now propose to prove the following theorem: At a point P_x on a surface the locus of the point (6) for a line $\bar{L}_1(a,b)$ which is the cusp-axis of a variable pencil of conjugate nets on the surface is the quadric of Wilczynski.

The curvilinear differential equation of any conjugate net N_λ on the surface S can be written in the form

$$(7) \quad dv^2 - \lambda^2 du^2 = 0 \quad (\lambda \neq 0),$$

where λ is a function of u, v . Let us denote the two curves of the net N_λ that pass through the point P_x by C_λ and $C_{-\lambda}$ according as the direction dv/du has the value λ or $-\lambda$. The curvilinear differential equation of the pencil of conjugate nets determined by the net (7) is

$$(8) \quad dv^2 - \lambda^2 h^2 du^2 = 0 \quad (h \neq 0),$$

where h is a constant. By a hypergeodesic is meant a curve C_λ which satisfies a differential equation of the form

$$(9) \quad \lambda' = A + B\lambda + C\lambda^2 + D\lambda^3 \quad (\lambda' = \lambda'_u + \lambda\lambda'_v),$$

in which the coefficients A, B, C, D are functions of u, v . To each such family of hypergeodesics is associated a cusp-axis, which is the line $\bar{L}_1(a,b)$ for which

$$(10) \quad a = \frac{1}{2}(\theta_v + C), \quad b = \frac{1}{2}(\theta_u - B).$$

If equation (8) is solved for h , and if h is then eliminated by total differentiation with respect to u , it becomes apparent that the curves of a pencil of conjugate nets constitute a family of hypergeodesics for which

$$(11) \quad A=D=0, \quad B = \lambda_u/\lambda, \quad C = \lambda_v/\lambda.$$

Moreover, the cusp-axis at the point P_x is the line $\bar{L}_1(a,b)$ for which a and b are given by the formulas

$$(12) \quad a = \frac{1}{2}(\theta_v + \lambda_v/\lambda), \quad b = \frac{1}{2}(\theta_u - \lambda_u/\lambda).$$

With these expressions for a and b , the coordinates of the point defined by equations (6) become

$$(13) \quad \begin{aligned} x_1 &= \frac{1}{4}(\theta_v + \lambda_v/\lambda)(\theta_u - \lambda_u/\lambda) - \frac{1}{2}\theta_{uv}, \\ x_2 &= -\frac{1}{2}(\theta_v + \lambda_v/\lambda), \\ x_3 &= -\frac{1}{2}(\theta_u - \lambda_u/\lambda), \\ x_4 &= 1. \end{aligned}$$

Finally, homogeneous elimination of λ yields the equation of the quadric of Wilczynski

$$(14) \quad x_2 x_3 - x_1 x_4 - \frac{1}{2}\theta_{uv} x_4^2 = 0.$$